

# **Belt Weigher Instrument MW95A Technical Information ALL**

# **ModWeigh**

- Flowrate measurement for belt weighers
- **Flowrate Output**
- **Material Totaliser**
- Modbus communications (independent RS232 and RS485 ports)
- **USB Host & Device (memory stick & PC)**
- Field software upgrades
- 12-24Vdc power supply
- Overall accuracy better than 0.01%

### MD2,MP2 INDICATOR

- **IP54 Facia**
- 2.8" (70mm) colour LCD
- 320 x 240 pixels
- Polyester film tactile keypad
- 4-20mA output, 1 digital input & 2 digital outputs

### MO3 I/O for MP2

- 4 Digital inputs
- 4 Digital outputs
- 4-20mA input (or 0-10V)
- 4-20mA output

### MD1,MP1 INDICATOR

- **IP65 Facia**
- 4.3" (109mm) colour LCD
- 480 x 272 pixels
- Silicone tactile keypad

### MT1 TRANSMITTER

- Size 136 x 66 x 50mm
- Optional removable P-Module holds calibration settings



### MT3 TRANSMITTER

Size 136 x 66 x 50mm

- Size 136 x 66 x 30mm
- 8 Digital inputs
- 8 Digital outputs
- 4-20mA input (or 0-10V)
- 4-20mA output x 2
- **Pulse output**

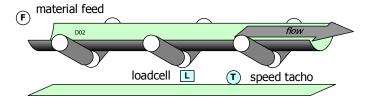
### Application

A ModWeigh MW95 Belt Weigher System is used to measure the flowrate of material carried by a belt conveyor.

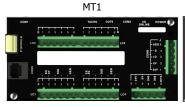
It measures the belt loading and belt speed and calculates the material flowrate.

### **ModWeigh Display**

A ModWeigh Flowrate Indicator is used to calibrate the system and provide a status display of the operating system. It has a graphics display with easy to use menu selection of settings.

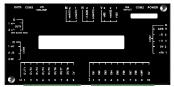








MR1



## **Features**

### Basic

### **Units & Resolution**

The units for each variable type (weight etc.) can be selected from a list of metric and imperial units. The resolution of each variable type can be adjusted, this alters the count by e.g 100kg displayed in 0.2kg increments.

### **OIML Design**

The instrument is designed to OIML standards.

### Language Support

Support is available for the following languages: English, Chinese, Korean, German, Spanish, French, Italian and Polish.

### **Inputs**

### **Digital Inputs INx**

The digital inputs are programmable to a range of function including 'acquire zero', 'print' etc.

### **Direct & Dynamic Calibration**

Direct calibration uses the loadcell capacity and loadcell sensitivity to calibrate the weight signal. Dynamic calibration allows calibration of the weight while the belt is moving knowing the platform weight (kg) or the belt loading (kg/m). This is useful when calibrating is done using chains.

### Corner Adjustment (MT1 only)

The input sensitivity can be individually adjusted for up to 4 loadcells, allowing differences in loadcell sensitivities to be corrected.

### Four Loadcell Inputs (MT1 only)

Separate inputs are available for 4 loadcells allowing the signal of each to be monitored sperately. This provide an aid for load balancing across loadcells and also for fault finding.

### Tacho Input

The tacho input is used to measure the belt speed and belt travel. Basic calibration is done using a tacho constant setting.

The system can be used to calibrate the tacho by measuring the number of pulses as a known length of belt passes a point. Other belt lengths can be measured in a similar manner.

### Zeroing

The weight of the unloaded belt is averaged over one complete belt revolution and the resulting value is stored as the dynamic zero.

The zeroing can be semi-automated by using an output signal to stop the material feed onto the belt, waiting until the belt is empty, performing the zero averaging, restarting the feed and waiting until material has reached the weigh point before returning to flow control.

Auto zeroing continuously monitors the platform weight. Any small drift in the weight measurement or material build up on the weigh platform is automatically zeroed out. This ensures that with no product on the belt, a zero flowrate is recorded.

### Signal Filtering

Filtering for the weight can be adjusted to get the optimum compromise between reduction of plant vibration and response speed.

### **Internal Signals**

### Limits

The high and low limits have adjustable setpoints which may be programmed to operate on any internal signal.

### **Batching**

The system can be used to batch out a desired weight by stopping the feeder when the batch weight has been totalised. A pre-act is available to compensate for overrun.

### **Event Collection**

Process events are collected for operation with external equipment (PLCs etc.)

### **Memory Storage**

Allows a group of settings to be stored or recalled from memory. This can be used for example to store settings for different products. There are 20 memory locations with up to 4 settings in each.

### **Material Total**

The processor incorporates a totaliser which totalises the weight of material through the system. The totaliser can be reset to zero. A pulse output is available to operate external counters. A low flow cutout ensures that low flows do not cause false counts. The total is retained after a power failure.

The totaliser can be set to operate with 5, 6, 7 or 8 digits.

### Outputs

### **Material Flowrate**

An analog flowrate output signal is available for connection to other instruments.

### Analog I/O Scaling

The analog output range can be adjusted over the full 0 to 20mA range. The output will drive to a slight negative mA, allowing a live zero to be achieved when using a 0 to 20mA range. A voltage output is easily produced by connecting a resistor to the output.

In addition the analog output signal is selectable to come from any internal signal in the instrument e.g weight, flowrate etc.

### **Digital Outputs OUTx**

The digital outputs are programmable to operate from any internal signal. These signals include the digital input states, status conditions (running, paused etc) and any fault conditions that are detected. This makes it easy connect into other systems.

### **Communications & Display**

#### **Comms**

RS232 and RS485 ports are available. These are used to connect ModWeigh units together and also to connect to other systems. The protocol is either ASCII output for example to drive a printer or Modbus for interactive communications. Baud rates and node addresses are programmable.

USB host and device ports are available. This allows for example PC and USB flash drive connectivity. It can be used to update the units software, for data logging and for recording of the units settings.

### **Printouts & Macros**

Printouts can be triggered by a key press or set up to occur at set times during the day or week. Data may also be output continuously for data collection purposes. Data is output on the COM1 RS232 port. The content of the printouts is fully programmable using Macros.

Macros are programs used to customise printouts, but can also be used to perform arithmetic calculations. The Macro language also contains conditional terms for more advanced programming.

### **Display Customisation**

Locks may be set to prevent unauthorised use of the operator keys and restrict entry to the operator menu. The keys are individually lockable and optionally a passcode can be used to allow authorised operators to use the keys. Alternatively a confirmation of the key action can be requested. The operator MENU can be customised to make additional settings or signals available to the operator.

The contents of the main display can be set to suit any condition, from a comprehensive display showing all operating parameters to a simple display showing the basic signals.



### **Computer Connectivity**

ModWeigh instruments can be connected to a computer withan RS232 connection. Data can be sent to the PC at a preset rate. The data sent can be set up using macros.

There is also a command line interface which allows any of the settings and data to be read or written.

### **IO Summary**

	Digital Inputs (includes pulse input)	NAMUR pulse input option	Digital Outputs (includes pulse output)	Isolated Pulse Output	Isolated 4-20mA Inputs	Isolated 4-20mA Outputs	RS232	RS485	USB Host (Memory Stick)	USB Device (PC Cable)	Corner adjustment and bal- ancing for 4 loadcells	Trade approvals (MW95, MW96)
MP2,MO3	1+4	×	2+4	1	1	1+1	1	1	1	1	×	×
MP1,MR1	1+8	×	9	1	1	2	2	1	1	1	×	×
MD1,MT1,MR1	2+8	✓	1+9	1	1	2	2	2	1	1	✓	✓
MD2,MT1,MR1	2+8	✓	1+9	1	1	2	2	2	1	1	✓	✓
MD1,MT3	2	×	1	0	0	1	2	1	1	1	×	×
MD2,MT3	2	×	1	0	0	1	2	1	1	1	×	×
MD1,MT3,MR1	2+8	×	8	1	1	3	2	1	1	1	×	×
MD2,MT3,MR1	2+8	×	8	1	1	3	2	1	1	1	×	×

# **Specifications**

### Loadcell Input AI1

Input Range  $\pm 4 \text{ mV/V } (0-20\text{mV})$ 

Excitation 5 Vdc  $\pm 20$  %, 250 mA maximum current Signal processing rate 100 Hz (response time setting  $\leq 0.5$  s)

Input sensitivity 0.5  $\mu$ V/division maximum Zero range ±3 mV/V (±15 mV)

Zero drift  $\pm 0.02 \ \mu V + 0.0005 \ \%$  of deadload/°C typical

Span drift  $\pm 0.0005$  %/°C typical Non-linearity < 0.002 % of FS Input noise  $= 0.15 \mu Vp-p typical$ 

Filtering 0.04 s to 32.0 s response time adjustable

Sense voltage range 1-5 V

**Analog Input AI2** 

4-20mA input resistance <60  $\Omega$  0-10V input resistance >100 kΩ

Isolation galvanically isolated to 50Vac

Analog Outputs AO1 & AO2

Output range 0 to 20 mA (-0.2 mA to 21 mA, includes standard 4-20mA)

 $\begin{array}{ll} \text{Maximum load} & 1000\Omega \\ \text{Resolution} & 0.4 \ \mu\text{A} \end{array}$ 

Response time Loadcell response time setting + 20 ms

Voltage output Use an external resistor to convert mA to volts.

For example  $500\Omega$  gives 10 V at 20 mA.

Non-linearity <0.01~% Drift  $<2~\mu\text{A}/^\circ\text{C}.$ 

Isolation independently galvanically isolated to 50Vac

Pulse Input INO - frequency input

Maximum range 0.01Hz to 4 kHz
Typical operating range 10 to 1000 Hz

Minimum pulse width 50us

INO set to PNP

High voltage > 8 V Low voltage < 4 V Maximum voltage 32 V

Input load  $4 \text{ k}\Omega$  approximate

INO set to NAMUR

Terminal voltage 8 V

Switching threshold 1.55 mA Hysteresis 0.2 mA

Namur fault <0.1 mA or >6 mA

INO set to AC

Voltage range 0.2 to 50 Vac

### Digital Inputs INx (except IN0)

High voltage > 8 V Low voltage < 4 V Maximum voltage 32 V

Input load  $6 \text{ k}\Omega\text{approximate}$ Input type PNP output sensors

### **Pulse Output OUT0**

Max output current50 mAMax working voltage30V ac/dcMax frequency500 Hz

 $\begin{array}{ll} \mbox{Duty cycle} & 50 \% \pm 20 \% \mbox{ (f} \times 0.5 \mbox{ Hz)} \\ \mbox{Max output pulse time} & 1000 \mbox{ ms (f} < 0.5 \mbox{ Hz)} \end{array}$ 

Isolation galvanically isolated to 50 Vac

### Digital Outputs OUTx (except OUT0)

Max output current  $$\Sigma \ I_{\text{IOx}} < 0.25 \ A$$ 

Output voltage same as supply voltage

### Communications COM1, COM2 & COM3

COM1 Interface RS232

COM1 Handshake CTS can be enabled

COM2/COM3 Interface RS485

Baud rates 9600, 19200, 38400, 57600, 115200 (230400 on COM2)

Settings 8 data bits, no parity, 2 stop bits (8-N-2)
Protocol Modbus RTU (MWBUS on COM2)

### General

IP Rating IP20 (MD1,MP1 facia IP65) (MD2,MP2 facia IP54)

Operating temperature -10 to 45 °C Supply voltage 10 to 28 Vdc

Power MT1 1.0 to 2.2 W +  $P_{Tacho Excitation}$ Power MT3 1.0 to 2.2 W +  $P_{Tacho Excitation}$ Power MR1 1.5 to 2.5 W +  $P_{OUTx}$ 

 Power MD1
 1.8 W

 Power MP1
 1.8 to 3.0 W

 Power MD2
 1.4 W

 Power MP2
 1.4 to 3.1 W

Power MP2 + MO3 3.4 to 5.0 W +  $P_{OUTx}$  +  $P_{Tacho Excitation}$  MP2 Restrictions  $P_{Loadcell Excitation}$  +  $P_{AO1}$  +  $P_{AO2}$  < 1.5 W

 $I_{\text{Supply}} < 0.5 \text{ A}$ 

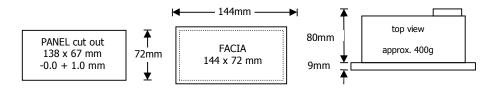
# **Dimensions**

Following are the dimensions of the hardware items that make up the system.

The displays/processors are designed for panel mounting.

### MD2 Display MP2 Processor





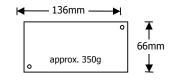
# MD1 Display MP1 Processor

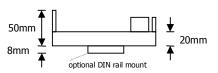




### **MT1 Transmitter**



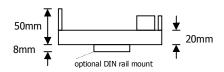




### **MT3 Transmitter**

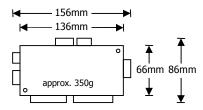


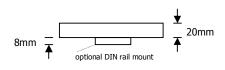




### **MR1 Remote IO**







# **Connections**

### **Connection Principles**

ModWeigh instruments can be configured in many different ways to suit any given application.

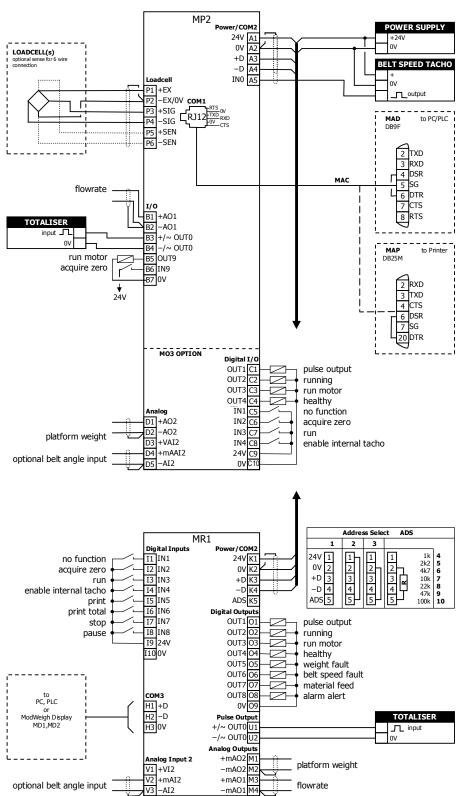
The display is normally located to suit an operator. The transmitter can be located in the field to reduce field wiring or can be located with the display for a more conventional approach.

The I/O can conveniently be situated on a DIN rail in a cabinet.

### Connection Diagram - MP2

Keep all wiring separated from mains wiring

Use shielded cable where indicated



### **Connection Diagram - MP1**

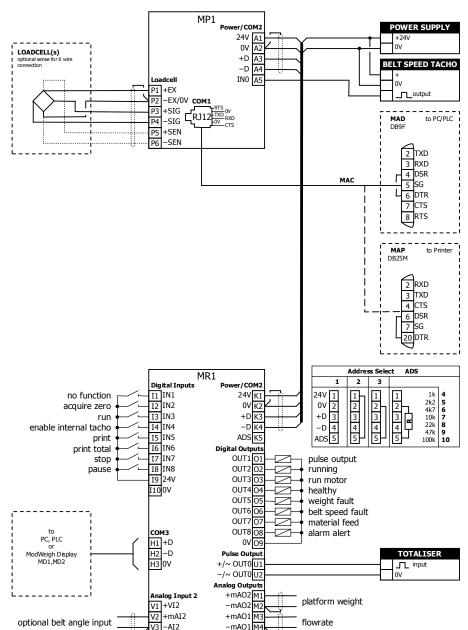
Keep all wiring separated from mains wiring

Use shielded cable where indicated

MP1 bus address set with setting (Q2522).

MR1 bus address set with ADS pin and must be same as MP1.

Fit an MAT terminator to each end of COM2 cable if length exceeds 50m.



### **Connection Diagram - MT1**

Keep all wiring separated from mains wiring.

Use shielded cable where indicated.

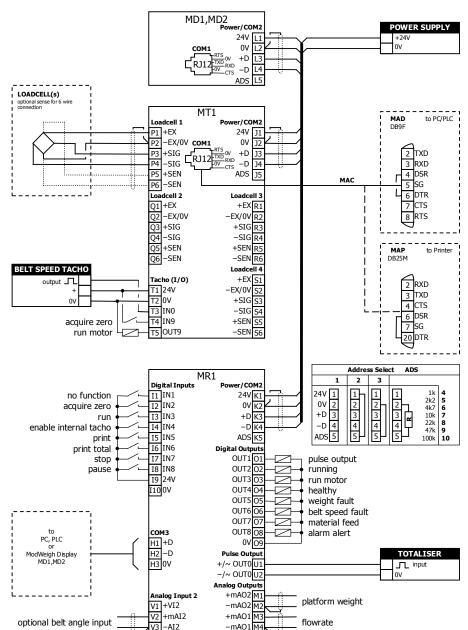
For individual loadcell sensitivity adjustment, use terminals P, Q, R and S.

Display and transmitter can alternatively be connected COM1 to COM1 using an MAC cable.

MT1 bus address set with ADS pin or a setting.

MR1 bus address set with ADS pin and must be same as MT1.

Fit an MAT terminator to each end of COM2 cable if length exceeds 50m.



### Connection Diagram - MT3

Keep all wiring separated from mains wiring.

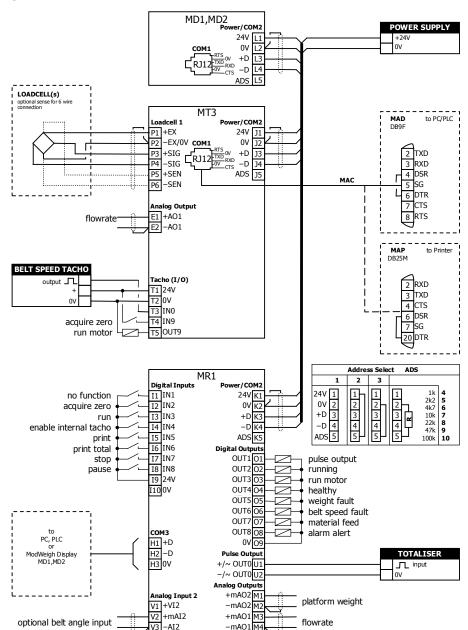
Use shielded cable where indicated.

Display and transmitter can alternatively be connected COM1 to COM1 using an MAC cable.

MT3 bus address set with ADS pin or a setting.

MR1 bus address set with ADS pin and must be same as MT3.

Fit an MAT terminator to each end of COM2 cable if length exceeds 50m.



# **System Ordering**

A ModWeigh system is a group of ModWeigh parts that together form the system. Many possible systems can be created, but most applications will use one of the systems listed below. When ordering, just specify the system order code. To create a custom system, specify the individual components required

Belt Weigher Instrument	System Order Code
Product Key, Processor, IO	MK95A,MP2
Oktober   Okto	
Product Key, Processor, IO	MK95A,MP2,MO3
Product Key, Processor, IO	MK95A,MP1,MR1
Transmitter, display, IO	MW95A,MT3,MD1,MR1
Transmitter, display, IO	MW95A,MT3,MD2,MR1
P-Module, transmitter, display, IO	MW95A,MT1,MD1,MR1
P-Module, transmitter, display, IO	MW95A,MT1,MD2,MR1

# **Parts Ordering**

Following is a list of order codes for the individual parts of a ModWeigh system.



The order code (and options) are shown below.	
select one of the following	
P-Module (for transmitter only)	MW95A
Unactivated P-Module (requires a product key)	MX95A
Product Key	МК95А

## **Special Options**



select any (or none) of the following	
Chinese manuals	,CH
Korean manuals	,КО
German manuals	,DE
Spanish manuals	,ES
French manuals	,FR
Italian manuals	,IT
Polish manuals	,PL
No manuals	,NM
Manufacturing certificate	,MC

### **Processor**





### **Transmitter**



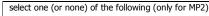


# select one (or none) of the following

Loadcell processor Loadcell processor Loadcell transmitter Loadcell transmitter ,MP2 ,MP1 ,MT3 ,MT1

### **IO Option**





digital IO - 4In 4Out, 1 x 4-20mA input & output

,MO3

### Display





### select one (or none) of the following

4.3" Colour display 2.8" Colour display

,MD1 ,MD2

### **Remote IO**



select one (or none) of the following

Remote IO unit

,MR1

,MAC

### Accessories



### select one (or none) of the following

Stack mount kit for MT1,MT3 or MR1

RJ12 Cable 2m (COM1 cable)

RJ12 to 9 pin D-connector adaptor (ModWeigh to PC)
RJ12 to 25 pin D-connector adaptor (ModWeigh to printer)
DIN Rail mount kit for MT1,MT3 or MR1

RS485 Line Terminator

,MAD ,MAP ,MAR ,MAS ,MAT

### **Other ModWeigh Products**

**MW61** Weigher Systems – loadcells indicators. Suitable for scales, vessel weighing and most general weighing applications.

MW93 Weight Change Systems – for loss-in-weight and gain-in-weight flow control systems.

**MW94** Impact Weigher Systems – impact weigher processor for continuous flowrate measurement.

**MW96** Weighfeeder Systems – weighfeeder processor for continuous flowrate control application of a weighing conveyor.

# **Contact Details**



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As we are continuously improving our products, changes to this specification may occur without notice. (Document Details:  $g0 g_1 g_2 g_3 g_4 g_5 g_6 g_7 g_8 g_9 g_10 g_11 g_12 g_13 g_14 g_15$  MTI,MT3,MD1,MD2,MP1,MP2))